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STABILIZATION OF PARTIAL DIFFERENTIAL EQUATIONS BY  
FINITE DIMENSIONAL BOUNDARY FEEDBACK CONTROL:

A pseudo-differential approach.

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**ABSTRACT.**

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ABSTRACT

We consider stabilization of Dirichlet evolution boundary problems by finite dimensional boundary feedback. A pseudo-differential operator method is used to transform the original operator domains into "classical" domains, where standard operator theory can be employed.

§ 1: INTRODUCTION.

We consider stabilization of parabolic and hyperbolic partial differential equations of the form

$$\left\{ \begin{array}{l} \partial_t u + Au = 0 \quad \text{in } \Omega, \quad \text{for } t > 0 \\ \gamma u = 0 \quad \text{on } \Gamma, \quad \text{for } t > 0 \\ u = u_0 \quad \text{in } \Omega, \quad \text{at } t = 0. \end{array} \right. \quad (1.1)$$

$$\left\{ \begin{array}{l} \partial_t^2 u + Au = 0 \quad \text{in } \Omega, \quad \text{for } t \in \mathbb{R} \\ \gamma u = 0 \quad \text{on } \Gamma, \quad \text{for } t \in \mathbb{R} \\ u = u_0 \quad \text{in } \Omega, \quad \text{at } t = 0 \\ \partial_t u = u_1 \quad \text{in } \Omega, \quad \text{at } t = 0 \end{array} \right. \quad (1.2)$$

$A$  is formally selfadjoint, uniformly strongly elliptic differential operator of order  $2m$  with  $C^\infty$ -coefficients on a bounded, open domain  $\Omega \subset \mathbb{R}^n$ , with smooth boundary  $\partial\Omega = \Gamma$ . Here  $\gamma = \{\gamma_j\}_{0 \leq j < m}$  is the Dirichlet trace operator.

$$\gamma_j u = \left[ \frac{\partial}{\partial n} \right]^j u \Big|_\Gamma \quad (1.3)$$

We denote similarly  $\nu = \{\nu_j\}_{m \leq j < 2m}$  the Neumann trace operator.

The Dirichlet realization  $A_\gamma$  of  $A$  is the operator acting like  $A$  in  $L^2(\Omega)$  and with domain

$$D(A_\gamma) = \{u \in H^{2m}(\Omega) \mid \gamma u = 0\} = H^{2m}(\Omega) \cap H_0^m(\Omega) . \quad (1.4)$$

where  $H^s(\Omega)$  is the Sobolev space of  $L^2$ -functions with  $L^2$ -derivatives up to order  $s$ . It is well known that  $A_\gamma$  is an unbounded, selfadjoint operator in  $L^2(\Omega)$ , with a sequence of real eigenvalues  $\lambda_1 \leq \lambda_2 \leq \dots \rightarrow \infty$ . We see that (1.1) and (1.2) are the time dependent evolution problems associated with  $A_\gamma$ , generalizing the heat equation resp. the wave equation. When  $\lambda_1 > 0$ , all solutions  $u(t,x)$  of (1.1) are exponentially decreasing for  $t \rightarrow \infty$ , and all solutions  $u(t,x)$  of (1.2) are bounded, we call this the stable case. However, if some eigenvalues are negative, there are solutions, both of (1.1) and (1.2), that blow up exponentially for  $t \rightarrow \infty$ . It is therefore of interest to investigate how one can change the systems to obtain the stable case.

By a perturbation of the first kind of the system (1.1), we will understand a system of the form

$$\begin{cases} \partial_t u + Au + Gu = 0 & \text{in } \Omega, \text{ for } t > 0 \\ \gamma u = 0 & \text{on } \Gamma, \text{ for } t > 0 \\ u = u_0 & \text{in } \Omega, \text{ at } t = 0 \end{cases} \quad (1.5)$$

where the interior operator  $A$  is replaced by  $A + G$ , where  $G$  has finite rank.

Stabilization of the a priori unstable system (1.1) by a perturbation of the first kind has been studied e.g. in Nambu [9] and Triggiani [11].

It is shown there that under suitable circumstances, it is possible to choose  $G$  of finite rank, such that (1.5) is stable.

By a perturbation of the second kind of the system (1.1), we will understand a system of the form

$$\left\{ \begin{array}{l} \partial_t u + Au = 0 \quad \text{in } \Omega, \quad \text{for } t > 0 \\ \gamma u = T'u \quad \text{on } \Gamma, \quad \text{for } t > 0 \\ u = u_0 \quad \text{in } \Omega, \quad \text{at } t = 0 \end{array} \right. \quad (1.6)$$

where the boundary operator  $\gamma$  is replaced by  $\gamma - T'$ ,  $T'$  being of finite rank. More specifically,  $T'$  is an operator applied to functions  $u$  on  $\Omega$ , whereas  $G$  should be an operator on the boundary values at  $\Gamma$  (the relevant boundary values are the Cauchy-data,  $[u = \{\gamma u, \nu u\}]$ , i.e.  $G$  is of the form  $K\zeta$ , where  $K$  maps from the boundary to the interior.

We define perturbations of the system (1.2) analogously.

We will refer to (1.5) and (1.6) as boundary feedback systems, when  $T'$  is of the special form

$$T'u = \sum_{j=1}^N (u|w_j)g_j \quad (1.7)$$

(here  $(\cdot|\cdot)$  is the usual  $L^2(\Omega)$ -inner product,  $w_j \in C^\infty(\bar{\Omega})$ ,  $g_j \in C^\infty(\Gamma)^m$ ,  $j = 1, 2, \dots, N$ ) and  $T'$  is called a finite dimensional feedback operator.

Boundary feedback systems have been studied in a number of papers by I. Lasiecka and R. Triggiani (see e.g. Lasiecka & Triggiani [6] and [7]). The main result is, that it is possible to choose the functions  $w_j$  and  $g_j$ , appearing in (1.7), such that the system (1.6) is stable. Lasiecka & Triggiani take a semigroup approach to investigate the system (1.6), using developments on the semigroup approach presented in Washburn [12] and Balakrishnan [1]. (The basic idea of a semigroup model is presented in Fattorini [3], where ordinary differential equations are considered.)

In the following we present a pseudo-differential operator method to investigate the system (1.6), with  $T'$  given by (1.7). This gives, in a simple way, the results of Lasiecka & Triggiani, as well as a similar result for the associated hyperbolic problem

$$\left\{ \begin{array}{l} \partial_t^2 u + Au = 0 \quad \text{in } \Omega, \quad \text{for } t \in \mathbb{R} \\ \gamma u = T'u \quad \text{on } \Gamma, \quad \text{for } t \in \mathbb{R} \\ u = u_0 \quad \text{in } \Omega, \quad \text{at } t = 0 \\ \partial_t u = u_1 \quad \text{in } \Omega, \quad \text{at } t = 0 \end{array} \right. \quad (1.8)$$

Here we would like to point out that there now exists a quite general theory that includes all the above perturbations when they have "smooth coefficients", namely the theory of pseudo-differential boundary problems. For these, the solvability of parabolic problems like (1.6) (and far more general cases) has been discussed in great detail in Grubb [4]. However, in the work that follows, we use only some basic results of the pseudo-differential methods, but the techniques are crucial for the simplicity of the proofs, and the theory is very helpful for the understanding of the underlying problems.

Our main result is that we can, in general, transform a perturbation of the second kind into a perturbation of the first kind, whenever the boundary condition is normal, in the sense described in Grubb [4]. This includes the "classical" normal boundary conditions, as well as the feedback boundary condition  $\gamma u - T'u = 0$ , with  $T'$  given by (1.7). In this case, however, a special transformation of the systems (1.6) and (1.8) into systems of the first kind proves to be very useful. It turns out that the transformation can be regarded as a generalized change of coordinates, and the resulting, transformed system operator  $A + G$  is merely a finite-dimensional,  $A$ -bounded perturbation of  $A$ . In this case, stabilization theory for perturbations of the first kind is straightforward, as we can apply the well known "pole assignment theorem", due to Wonham (see Wonham [13]). The operator  $G$  in  $A + G$  is a so-called singular Green operator, it is of a pseudo-differential nature, and since our developments also involve manipulations with other pseudo-differential operators, we will briefly introduce some facts and terminology concerning them, for the benefit of the reader unfamiliar with these operators. For details we refer to Grubb [4]. (and Hörmander [5] for the interior pseudo-differential operators).

## § 2: SOME FACTS ABOUT PSEUDO-DIFFERENTIAL OPERATORS.

A pseudo-differential operator  $P$  of order  $d \in \mathbb{R}$ , defined on  $\mathbb{R}^n$  (or on a neighborhood of  $\bar{\Omega}$ ) is a special kind of (singular) integral operator, defined by the formula

$$Pu(x) = (2\pi)^{-n} \int_{\mathbb{R}^n} e^{ix\xi} p(x,\xi) \hat{u}(\xi) d\xi, \quad (2.1)$$

where  $\hat{u}$  is the Fourier transform of  $u$ , and where the symbol  $p(x,\xi)$  is a  $C^\infty$ -function, developed in a series of terms  $p^j(x,\xi)$ ,  $j \in \mathbb{N}$ , homogeneous of degree  $d-j$  in  $\xi$ , for  $|\xi| \geq 1$ , of which  $p(x,\xi)$  is a kind of asymptotic sum.

Example 2.1.

The differential operator

$$Au(x) = \sum_{|\alpha| \leq 2m} a_\alpha(x) D^\alpha u(x) \quad (2.2)$$

with  $C^\infty(\bar{\Omega})$  coefficients, can be written ( $F^{-1}$  is the inverse Fourier transform)

$$\begin{aligned} Au(x) &= \sum_{|\alpha| \leq 2m} a_\alpha(x) F^{-1} [F^\alpha \hat{u}(F)] \quad (2.3) \\ &= (2\pi)^{-n} \int_{\mathbb{R}^n} e^{ix \cdot F} \sum_{|\alpha| \leq 2m} a_\alpha(x) F^\alpha \hat{u}(F) dF, \end{aligned}$$

so  $A$  is a pseudo-differential operator of order  $2m$ , with symbol  $p(x, F) = \sum_{|\alpha| \leq 2m} a_\alpha(x) F^\alpha$ .

[Note also that (2.1) can be written

$$Pu(x) = (2\pi)^{-n} \int_{\mathbb{R}^{2n}} e^{i(x-y) \cdot F} p(x, F) u(y) dy dF. \quad (2.4)$$

The truncated operator  $P_\Omega$  over  $\Omega$  is defined by

$$P_\Omega = r_\Omega P e_\Omega \quad (2.5)$$

where  $e_\Omega$  denotes extension by zero on  $\mathbb{R}^n \setminus \Omega$  and  $r_\Omega$  denotes restriction from  $\mathbb{R}^n$  to  $\Omega$ . Pseudo-differential operators over the  $(n-1)$ -dimensional manifold  $\Gamma$  are defined from pseudo-differential operators on  $\mathbb{R}^{n-1}$ , using local coordinates.

Poisson operators  $K$  from  $\mathbb{R}^{n-1}$  to  $\mathbb{R}_+^n$  of order  $d \in \mathbb{R}$  basically takes on the following form

$$Kv(x) = (2\pi)^{1-n} \int_{\mathbb{R}^{n-1}} e^{ix' \cdot F'} \tilde{k}(x', x_n, F') \hat{v}(F') dF', \quad (2.6)$$

where we apply the standard notation

$$x = (x_1, x_2, \dots, x_n) = (x', x_n) . \tag{2.7}$$

Here  $\tilde{k} \in C^\infty$  satisfies suitable estimates, and is also a series of (quasi) homogeneous terms. Poisson operators from  $\Gamma$  to  $\Omega$  are defined similarly, by the help at local coordinates.

A trace operator  $T$  of order  $d \in \mathbb{R}$  from  $\Omega$  to  $\Gamma$ , is an operator of the form

$$Tu = \sum_{0 \leq j \leq \ell-1} S_j \gamma_j u + T'u \tag{2.8}$$

where the  $\gamma_j$  are the usual trace operators

$$\gamma_j = \left[ \frac{\partial}{\partial n} \right]^j \tag{2.9}$$

and the  $S_j$  are pseudo-differential operators on  $\Gamma$  of order  $d-j$ .  $T'$  is a special kind of trace operator that in local coordinates (where  $\Omega$  and  $\Gamma$  are replaced by  $\mathbb{R}_+^n$  and  $\mathbb{R}^{n-1}$ ) has the form

$$T'u(x') = (2\pi)^{1-n} \int_{\mathbb{R}^{n-1}} e^{ix' \cdot \xi'} \int_0^\infty \tilde{t}'(x', x_n, \xi') \hat{u}(\xi', x_n) dx_n d\xi' . \tag{2.10}$$

Here  $\hat{u}(\xi', x_n)$  denotes the partial Fourier transform  $F_{x' \rightarrow \xi'} u(x', x_n)$ , and  $\tilde{t}'$  is a function of the same type as the  $\tilde{k}$  above. The number  $\ell$  in (2.8) is called the class of  $T$ .

Finally, a singular Green operator  $G$  of order  $d \in \mathbb{R}$  and class  $\ell \in \mathbb{N}$  on  $\Omega$  is an operator

$$Gu = \sum_{0 \leq j \leq \ell-1} K_j \gamma_j u + G'u \tag{2.11}$$

where the  $K_j$  are Poisson operators of order  $d-j$ .

$G'$  has the form (in local coordinates)

$$G'u(x) = (2\pi)^{1-n} \int_{\mathbb{R}^{n-1}} e^{ix' \cdot \xi'} \int_0^\infty \tilde{g}'(x', x_n, y_n, \xi') \hat{u}(\xi', y_n) dy_n d\xi' . \tag{2.12}$$



where  $\tilde{g}$  is a  $C^\infty$ -function, satisfying appropriate estimates. Singular Green operators arise typically when Poisson and trace operators are composed.

One of the advantages of using the pseudo-differential calculus is that composition and inversion of operators is worked out in a systematic way, once and for all; and that these operations are closely linked with the "symbolic calculus", i.e. the calculus for the associated constant coefficient cases by the help of the Fourier transform.

### § 3: TRANSFORMATION.

We will now introduce a transformation that will help us in solving the stabilization problem (see Grubb [4], lemma 1.6.8). Define the trace operator  $T$  by

$$T = \gamma - T' \quad (3.1)$$

where  $T'$  is given by (1.7). The realization  $A_T$  of  $A$  is the operator acting like  $A$ , with domain

$$D(A_T) = \{u \in H^{2m}(\Omega) \mid Tu = 0\} . \quad (3.2)$$

Now according to Grubb, there exists an operator  $\Lambda$ , which is a homeomorphism in  $H^s(\Omega)$  for any  $s \geq 0$ , such that  $\Lambda$  defines a bijection

$$\Lambda: D(A_T) \xrightarrow{\sim} D(A_\gamma) . \quad (3.3)$$

where  $D(A_\gamma)$  is the domain of the Dirichlet realization introduced in § 1. Then, applying the techniques from Grubb [4] we find that  $A_T$  is (obviously) densely defined, and closed.

Now consider, for  $\ell = 1, 2$ , the parabolic, resp. hyperbolic perturbation of the second kind

$$\partial_t^\ell u + A_T u = 0 \quad , \quad u \in D(A_T) . \quad (3.4)$$

Using (3.3), this can be transformed into

$$\partial_t^\ell \Lambda^{-1} v + A_T \Lambda^{-1} v = 0 \quad , \quad v \in D(A_\gamma) \quad (3.5)$$

where  $v = \Lambda u$

Acting with  $\Lambda$  from the left in (3.5) we find

$$\partial_t^\ell v + \Lambda \Lambda_T \Lambda^{-1} v = 0, \quad v \in D(\Lambda_T). \quad (3.6)$$

It can be shown that  $\Lambda \Lambda_T \Lambda^{-1}$  has the form

$$\Lambda \Lambda_T \Lambda^{-1} = \Lambda + G \quad (3.7)$$

where  $G$  is a singular Green operator of finite rank, hence (3.6) is a perturbation of the first kind.

In this case, where  $T'$  is of the form (1.7), we have another, very useful, factorization

$$\Lambda_T = \Lambda_\gamma (1 - K_\gamma T') . \quad (3.8)$$

Here  $K_\gamma$  is the Poisson operator that solves the Dirichlet problem for  $\Lambda$ ,

i.e.  $u = K_\gamma \varphi$  is the solution of

$$\begin{cases} \Lambda u = 0 & \text{in } \Omega \\ \gamma u = \varphi & \text{on } \Gamma \end{cases} \quad (3.9)$$

(We assume, for the moment, that 0 is not an eigenvalue of  $\Lambda_\gamma$ ).

With our application in mind it is now important to notice that we can choose  $T'$ , such that  $1 - K_\gamma T'$ , like  $\Lambda$ , defines a homeomorphism

$$1 - K_\gamma T' : D(\Lambda_T) \xrightarrow{\sim} D(\Lambda_\gamma) . \quad (3.10)$$

The factorization (3.8) is now evident, since for  $v = (1 - K_\gamma T')u$ ,  $u \in D(\Lambda_T)$ , we have

$$\Lambda v = \Lambda u \quad (3.11)$$

because  $\Lambda_\gamma K_\gamma = 0$ .

Proceeding as above, we see that the problem

$$\partial_t^\ell u + \Lambda_T u = 0, \quad u \in D(\Lambda_T) \quad (3.12)$$

transforms into

$$\partial_t^2 v + (1 - K_\gamma T') A_\gamma v = 0 \quad , \quad v \in D(A_\gamma) \tag{3.13}$$

where  $v = (1 - K_\gamma T')u$ .

Thus we have transformed the perturbation of the second kind (3.12) into a perturbation of the first kind (3.13), and we are able to calculate the system operator.

We have

Theorem 3.1.

The boundary feedback systems

$$\left\{ \begin{array}{l} \partial_t u + Au = 0 \quad \text{in } \Omega \quad , \quad \text{for } t > 0 \\ \gamma u = T'u \quad \text{on } \gamma \quad , \quad \text{for } t > 0 \\ u = u_0 \quad \text{in } \Omega \quad , \quad \text{for } t = 0 \end{array} \right. \tag{3.14}$$

and

$$\left\{ \begin{array}{l} \partial_t^2 u + Au = 0 \quad \text{in } \Omega \quad , \quad \text{for } t \in \mathbb{R} \\ \gamma u = T'u \quad \text{on } \gamma \quad , \quad \text{for } t \in \mathbb{R} \\ u = u_0 \quad \text{in } \Omega \quad , \quad \text{at } t = 0 \\ \partial_t u = u_1 \quad \text{in } \Omega \quad , \quad \text{at } t = 0 \end{array} \right. \tag{3.15}$$

with  $T'$  given by (1.7), transforms into the systems

$$\left\{ \begin{array}{l} \partial_t v + Av - K_\gamma T'Av = 0 \quad \text{in } \Omega \quad , \quad \text{for } t > 0 \\ \gamma v = 0 \quad \text{on } \Gamma \quad , \quad \text{for } t > 0 \\ v = v_0 \quad \text{in } \Omega \quad , \quad \text{at } t = 0 \end{array} \right. \tag{3.14'}$$

and

$$\left\{ \begin{array}{l} \partial_t^2 v + Av - K_\gamma T'Av = 0 \quad \text{in } \Omega \quad , \quad \text{for } t \in \mathbb{R} \\ \gamma v = 0 \quad \text{on } \Gamma \quad , \quad \text{for } t \in \mathbb{R} \\ v = v_0 \quad \text{in } \Omega \quad , \quad \text{at } t = 0 \\ \partial_t v = v_1 \quad \text{in } \Omega \quad , \quad \text{at } t = 0 \end{array} \right. \tag{3.15'}$$

Since

$$K_\gamma T' A v = \sum_{j=1}^N (A v | w_j) K_\gamma g_j \tag{3.16}$$

for  $v \in H^{2m}(\Omega)$ ,  $K_\gamma T' A$  has finite rank, and we see that  $\tilde{A} = A - K_\gamma T' A$  can be regarded as a finite dimensional perturbation of  $A$ . We obviously have

$$\|K_\gamma T' A v\|_{L^2} \leq c \|A v\|_{L^2} \leq c \|A v\|_{L^2} + \|v\|_{L^2} \tag{3.17}$$

for  $v \in D(A_\gamma)$ , so  $K_\gamma T' A$  is  $A$ -bounded.

Since  $A_\gamma$  is the infinitesimal generator of an analytic semigroup on  $L^2(\Omega)$  so is  $\tilde{A}_\gamma$ , using the perturbation result in Zabczyk [14], proposition 1.

We have

Theorem 3.2.

The realization  $\tilde{A}_\gamma$  of the operator

$$\tilde{A} = A - K_\gamma T' A \tag{3.18}$$

with domain

$$D(\tilde{A}_\gamma) = H^{2m}(\Omega) \cap H_0^m(\Omega) \quad (= D(A_\gamma)) \tag{3.19}$$

is the infinitesimal generator of an analytic semigroup  $e^{-\tilde{A}_\gamma t}$ ,  $t \geq 0$ , on  $L^2(\Omega)$ , giving the solution to (3.14') as

$$v(t, x) = e^{-\tilde{A}_\gamma t} v_0(x) \quad , \quad x \in \Omega \quad , \quad t \geq 0 \tag{3.20}$$

when  $v_0 \in L^2(\Omega)$ . The solution to the original system (3.14) is then

$$u(t, x) = (1 - K_\gamma T')^{-1} e^{-\tilde{A}_\gamma t} (1 - K_\gamma T') u_0(x) \quad , \quad x \in \Omega \quad , \quad t \geq 0 \tag{3.21}$$

when  $u_0 \in L^2(\Omega)$ .



#### § 4. STABILIZATION.

An application of the pseudo-differential transformation.

We will now show how the transformation from § 3 can be used as a shortcut to the results of Lasiecka and Triggiani ([6], [7], [8]), which have been of great inspiration to us.

The assumed instability of the systems (1.1) and (1.2), is caused by the negative eigenvalues in the pure point spectrum of  $A_\gamma$ , and we will show that we can choose a finite dimensional feedback boundary condition

$$\gamma u = T'u \quad (4.1)$$

where  $T'$  is defined by

$$T'u = \sum_{j=1}^N (u|w_j)g_j \quad (4.2)$$

(see (1.7)), such that the systems

$$\left\{ \begin{array}{l} \partial_t u + Au = 0 \quad \text{in } \Omega, \quad \text{for } t > 0 \\ \gamma u = T'u \quad \text{on } \Gamma, \quad \text{for } t > 0 \\ u = u_0 \quad \text{in } \Omega, \quad \text{at } t = 0 \end{array} \right. \quad (4.3)$$

and

$$\left\{ \begin{array}{l} \partial_t^2 u + Au = 0 \quad \text{in } \Omega, \quad \text{for } t \in \mathbb{R} \\ \gamma u = T'u \quad \text{on } \Gamma, \quad \text{for } t \in \mathbb{R} \\ u = u_0 \quad \text{in } \Omega, \quad \text{at } t = 0 \\ \partial_t u = u_1 \quad \text{in } \Omega, \quad \text{at } t = 0 \end{array} \right. \quad (4.4)$$

are stable systems (in the sense described in § 1). We will apply the pseudo-differential transformation to the perturbations of the second kind (4.3) and (4.4) and then apply Wonham's "pole assignment theorem" on the resulting systems of the first kind. This, combined with a classical resolvent analysis, gives us the desired results.

Let the eigenvalues of  $A_\gamma$  be arranged in a non-decreasing sequence

$$\lambda_1 \leq \lambda_2 \leq \dots \leq \lambda_{K-1} \leq 0 < \lambda_K \leq \dots \tag{4.5}$$

each eigenvalue repeated according to multiplicity, and let  $\{\varphi_j\}_{j \geq 1}$  be a corresponding set of orthonormalized eigenfunctions of  $A_\gamma$ . Now define  $P_u$  and  $P_s$  as the orthogonal projections of  $L^2(\Omega)$  on the orthogonal subspaces  $X_u$ , resp.  $X_s$ , defined by

$$\begin{cases} X_u = \text{span } \{\varphi_j\}_{1 \leq j < K} \\ X_s = \overline{\text{span } \{\varphi_j\}_{j \geq K}} \end{cases} \tag{4.6}$$

Remark 4.1.

The results in Lasiecka & Triggiani [6], [7] and [8] are formulated as if nonselfadjoint realizations are treated as well, but on the other hand the treatment is based heavily on the orthogonal projections on the eigenspaces  $X_u$  and  $X_s$  of  $A_\gamma$ . Orthogonality of eigenspaces in general requires at least that  $A_\gamma$  be normal, i.e.  $A_\gamma A_\gamma^* = A_\gamma^* A_\gamma$ , but we know of no Dirichlet realization  $A_\gamma$  satisfying this without being selfadjoint. ■

Since  $X_u$  and  $X_s \cap D(A_\gamma)$  are invariant subspaces for  $A_\gamma$ , we can define the restrictions

$$\begin{cases} A_u = A_\gamma|_{X_u} \\ A_s = A_\gamma|_{X_s \cap D(A_\gamma)} \end{cases} \tag{4.7}$$

Then  $A_u$  is a bounded operator on  $X_u$ , and  $A_s$  is an unbounded operator on  $D(A_s) = X_s \cap D(A_\gamma)$ . Notice that  $P_u$  and  $P_s$  commute with  $A_\gamma$  on  $D(A_\gamma)$ .

Now writing  $f_u = P_u f$ ,  $f_s = P_s f$  for  $f \in L^2(\Omega)$ , we have that when  $u \in D(A_T)$  (see (3.2) and (3.8)), then  $v = (1 - K_\gamma T')u \in D(A_\gamma)$  satisfies

$$\begin{cases} Av = Au \\ v_u \in X_u \\ v_s \in D(A_s) \end{cases} \quad (4.8)$$

We now use the factorization

$$A_T = A_\gamma (1 - K_\gamma T') \quad (4.9)$$

in the discussion of the resolvent equation

$$(A_T - \lambda)u = f, \quad f \in L^2(\Omega) \quad (4.10)$$

First we consider the case, where we are allowed to decouple the feedback by assuming that

$$P_s w_j = 0, \quad j = 1, 2, \dots, N \quad (4.11)$$

(i.e. the  $w_j$  are in  $X_u$ ; the "unstable" eigenspace).

Then the equation (4.10) reduces to the system

$$A_u u_u - A_u P_u K_\gamma T' u_u - \lambda u_u = f_u \quad (4.12)$$

$$-A P_s K_\gamma T' u_u + A u_s - \lambda u_s = f_s \quad (4.13)$$

where we observe that (4.12) is a finite dimensional resolvent equation for the matrix operator

$$\bar{A}_u = A_u - A_u P_u K_\gamma T' \quad (4.14)$$

To this we can apply Wonham's theorem to stabilize the unstable part of the system. We then have one of Lasiecka and Triggiani's results (in the case  $m = 1$ ):

Theorem 4.2.

Assume that the Neumann traces  $\{v\varphi_j\}_{1 \leq j < K}$  are linearly independent, so that

$$\dim (vX_u) = \dim(X_u) (= K-1) \tag{4.15}$$

and let  $\{c_j\}_{1 \leq j < K}$  be an arbitrary given set of  $K-1$  distinct, real numbers.

Then there exists a number  $N$  and a set  $\{w_j, g_j\}_{1 \leq j \leq N}$  where  $w_j \in X_u$  and  $g_j \in C^\infty(\Gamma)^m$ , such that with

$$T'u = \sum_{j=1}^N (u|w_j)g_j \tag{4.16}$$

the eigenvalues of the matrix operator

$$\bar{A}_u = A_u - A_u P_u K_\gamma T' \tag{4.17}$$

on  $X_u$ , are  $\{c_j\}_{1 \leq j < K}$ .

The number  $N$  of feedback terms can be taken as the largest multiplicity of the eigenvalues  $\{\lambda_j\}_{1 \leq j < K}$  of  $A_u$ . In particular,  $N = 1$  when the eigenvalues are simple. ■

Remark 4.3.

For the application of the Wonham theorem here, it is important that the range of  $P_u K_\gamma$  fills out all of  $X_u$ ; this can be reformulated as the question of whether the Neumann traces of the Dirichlet eigenfunctions in  $X_u$  are linearly independent. In that case the results are easy to formulate and allow  $N$  to be very low, otherwise the results become increasingly complicated and require higher  $N$ , the more linear dependence there is. ■

If we chose the poles  $\{c_j\}_{1 \leq j < K}$  occurring in Theorem 4.2 such that  $c_j \geq \lambda_K(\cdot) > 0$  and choose  $T'$  according to the theorem, we obtain after a classical resolvent analysis:



Lemma 4.4.

The resolvent  $R(\lambda, A_T)$  of  $A_T$  satisfies the inequality

$$\|R(\lambda, A_T)\|_{L^2, L^2} \leq \frac{c}{\text{dist}(\lambda, \text{co}(\text{sp}(A_T)))} \quad (4.18)$$

as an operator in  $L^2(\Omega)$ . Here  $c > 0$  is a constant independent of  $\lambda$ , and  $\text{co}(\text{sp}(A_T))$  is the convex hull of the spectrum of  $A_T$ . ■

We then have (for  $m = 1$ ) some of Lasiecka and Triggianis main results:

Theorem 4.5.

There exists a finite dimensional boundary condition

$$\tau u = T'u \quad \text{on } \Gamma \quad (4.19)$$

where

$$T'u = \sum_{j=1}^N (u|w_j)g_j. \quad (4.20)$$

$w_j \in X_u$ ,  $g_j \in C^\infty(\Gamma)^m$ ,  $j = 1, 2, \dots, N$ , such that the realization  $A_T$  of  $A$ , with domain

$$D(A_T) = \{u \in H^{2m}(\Omega) \mid Tu = \tau u - T'u = 0\} \quad (4.21)$$

is the infinitesimal generator of an analytic semigroup  $e^{-A_T t}$ ,  $t \geq 0$  on  $L^2(\Omega)$ , giving the solution the Dirichlet boundary feedback parabolic system (4.3) as

$$u(t, x) = e^{-A_T t} u_0(x), \quad x \in \Omega, \quad t \geq 0. \quad (4.22)$$

when  $u_0 \in L^2(\Omega)$ . The solution (4.22) satisfies

$$\|u(t, \cdot)\|_{L^2} \leq M e^{-\lambda_K t} \|u_0\|_{L^2}, \quad t \geq 0, \quad M > 0. \quad (4.23)$$

where  $\lambda_K$  is the first positive Dirichlet eigenvalue of  $A$ . Moreover, the operators

$$\cos(\Lambda_T^{1/2}t) \text{ and } \sin(\Lambda_T^{1/2}t) \quad (4.24)$$

are well defined, and we can write the solution to the hyperbolic system (4.4) as

$$u(t,x) = \cos(\Lambda_T^{1/2}t)u_0(x) + \Lambda_T^{-1/2}\sin(\Lambda_T^{1/2}t)u_1(x) \quad (4.25)$$

$x \in \Omega$ ,  $t \in \mathbb{R}$ , when  $u_0, u_1 \in L_2(\Omega)$ .

Remark 4.6.

One of the slightly mysterious facts about the perturbation of the second kind, is that the operator  $\Lambda_T$  can never be semibounded (i.e. satisfy an inequality  $\operatorname{Re} e^{i\theta}(\Lambda_T u|u) \geq c\|u\|_{L^2}^2$  for some  $c$  and  $\theta$ ), when  $T \neq 0$ .

This is a consequence of Proposition 1.7.11 in Grubb [4]. In particular,  $\Lambda_T$  can never be selfadjoint. Since  $\Lambda_T$  is never semibounded, the semigroup  $e^{-\Lambda_T t}$ ,  $t \geq 0$  is never a contraction semigroup, hence the constant  $M$  in (4.23) is always greater than 1. This is also noticed by Lastecka and Triggiani, who consider the translated Laplacian.

This is however not true for the Neumann problem.

Remark 4.7.

Comparison of Eqs. (4.22) and (3.21) shows that for the semigroups we have

$$e^{-\Lambda_T t} = (1 - K_\gamma T')^{-1} e^{-\tilde{\Lambda}_\gamma t} (1 - K_\gamma T') \quad (4.26)$$

This justifies the term "generalized change of coordinates" from § 1.

Now, it is straightforward to extend the theory to include more general cases, with only "weak" decoupling. If  $w_j \in C^\infty(\bar{\Omega})$ , with  $P_s w_j \neq 0$ , we can also obtain stabilization for small  $\|P_s w_j\|_{L^2}$ ; the pseudo-differential transformation can again be applied to prove the existence of a feedback semigroup  $e^{-A_T t}$ ,  $t \geq 0$  on  $L^2(\Omega)$ , giving the solution to the parabolic system (4.3) exactly as in (4.22). In the more general case, the solution satisfies

$$\|u(t, \cdot)\|_{L^2} \leq M' e^{-(\lambda_K - \epsilon)t} \|u_0\|_{L^2}, \quad t \geq 0. \quad (4.27)$$

$M' > 1, \epsilon > 0$ .

What is probably more surprising, is that if moreover the  $w_j$ 's are chosen so that  $P_s w_j$  are in  $D(A_\gamma)$  for  $j = 1, 2, \dots, N$ , the solution of the hyperbolic system (4.4) can be represented as in (4.25). This is basically because we can apply bounded perturbation theory (Sova [10], Fattorini [2]) in this case.

One of the forces of the pseudo-differential transformation, is that the problems are reduced to classical resolvent discussions in  $L^2(\Omega)$ , and it requires no use of the fractional powers spaces as e.g.  $D(A_\gamma^{-\alpha})$ ,  $0 \leq \alpha < \frac{1}{2}$ , that Lasiecka and Triggiani use. Therefore, our resolvent estimate (4.18), in the decoupled case, is sharper than the corresponding estimate in Lasiecka and Triggiani [7], hence our version of the exponential damping result (4.23) is a bit sharper than the original.

Remark 4.8.

If we allow simultaneous interference in the operator equation and the boundary condition, we obtain a perturbation of the third kind:

$$\left\{ \begin{array}{l} \partial_t u + Au + Gu = 0 \quad \text{in } \Omega, \text{ for } t > 0 \\ \tau u = T'u \quad \text{on } \Gamma, \text{ for } t > 0 \\ u = u_0 \quad \text{in } \Omega, \text{ at } t = 0. \end{array} \right. \quad (4.28)$$

where the operators  $G$  and  $T'$  are of the types considered above. In this way we can stabilize the system and we can construct the feedback so that the operator realization

considered is selfadjoint. ■

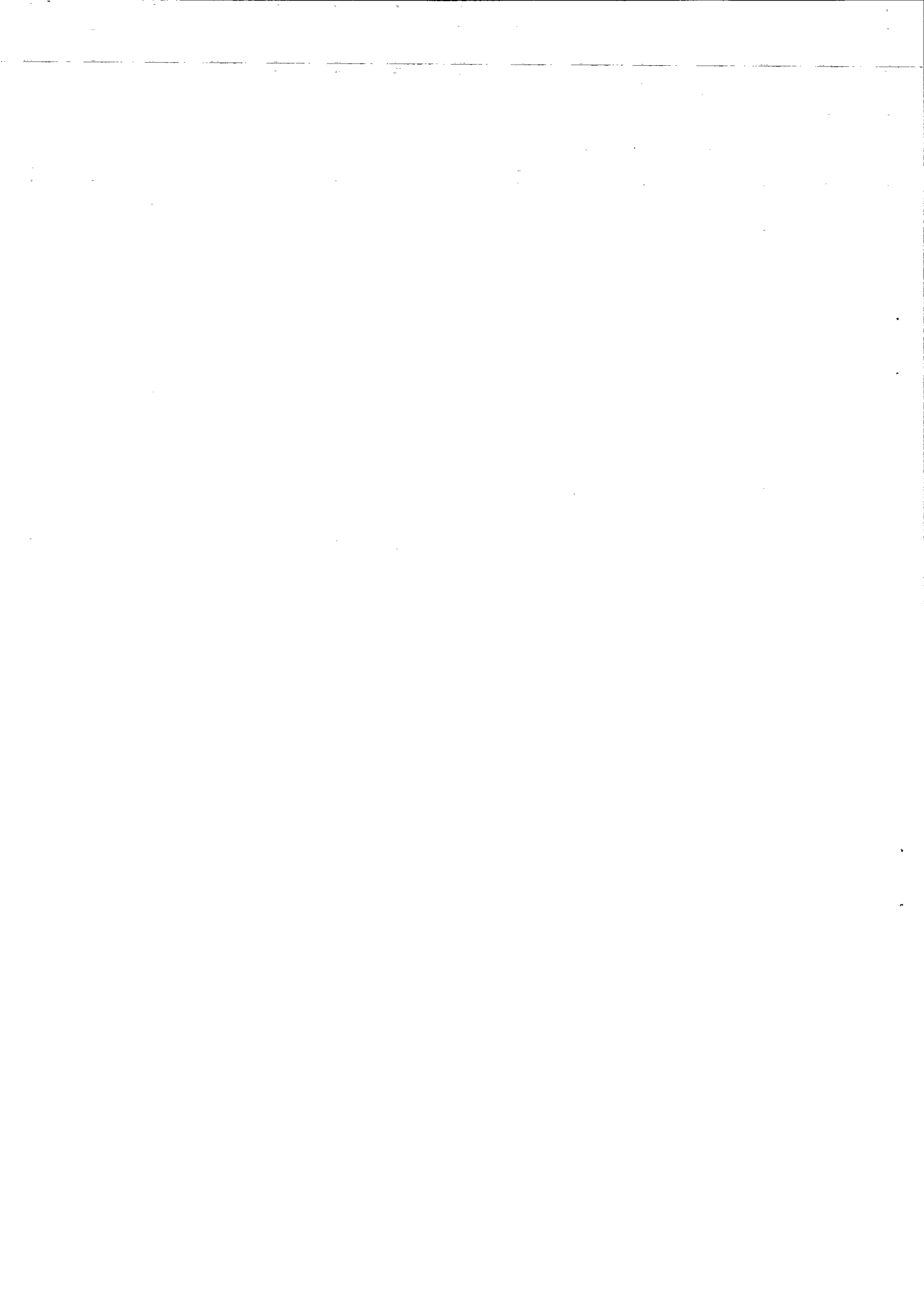
Final remark.

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